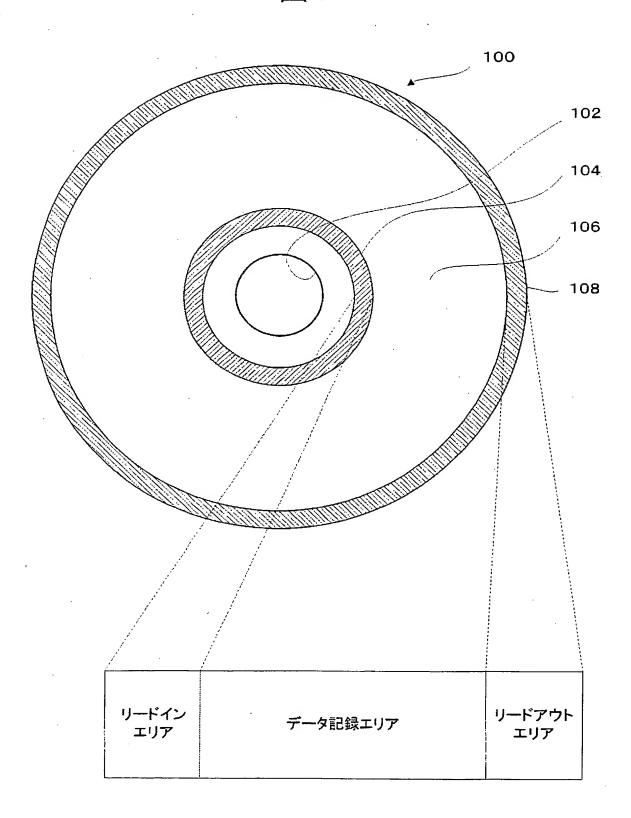
[図1]

図1



[図2]

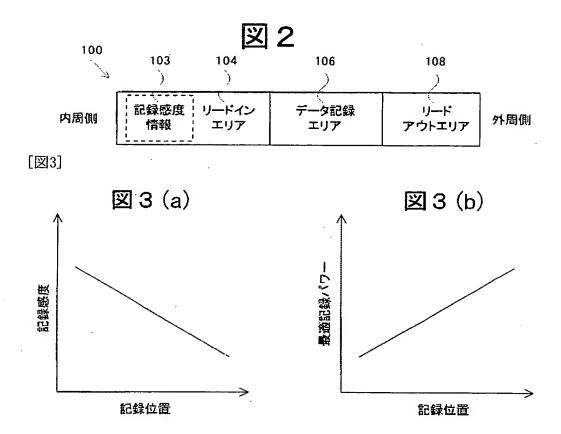
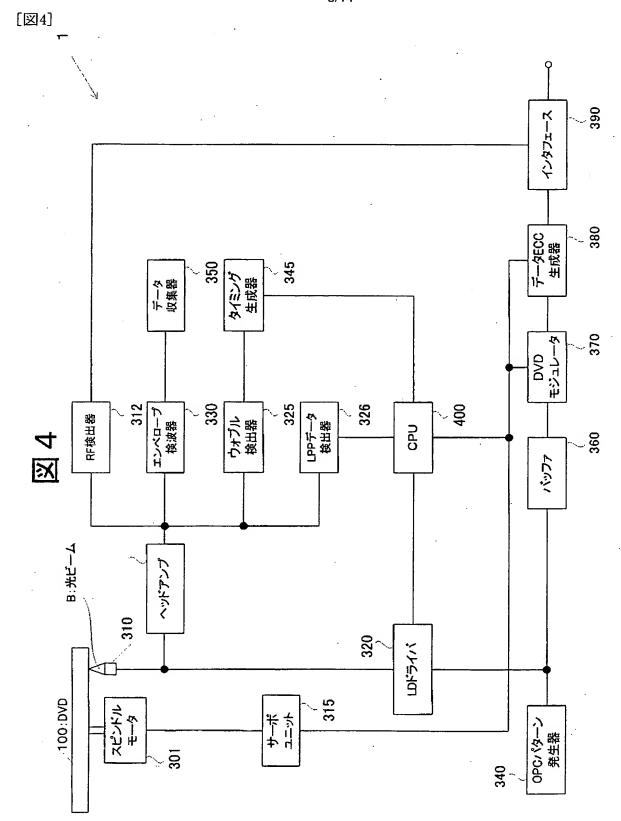
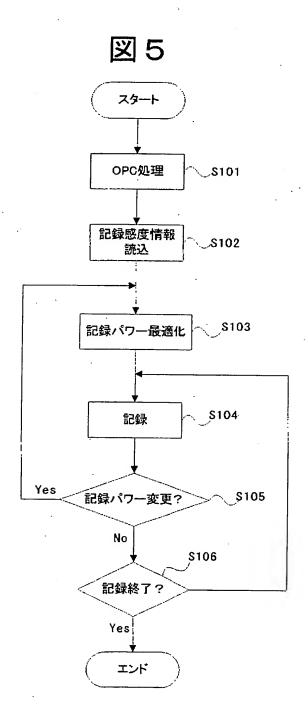


図3(c)

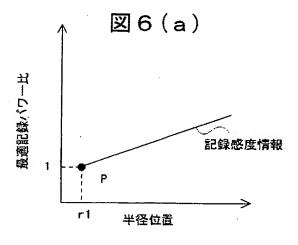
半径位置	記錄感度
r[1]	â
r[2]	b
•	С
r[n]	ď

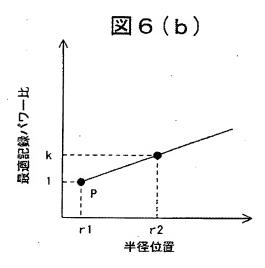


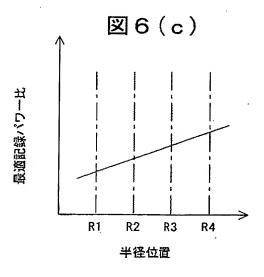
[図5]

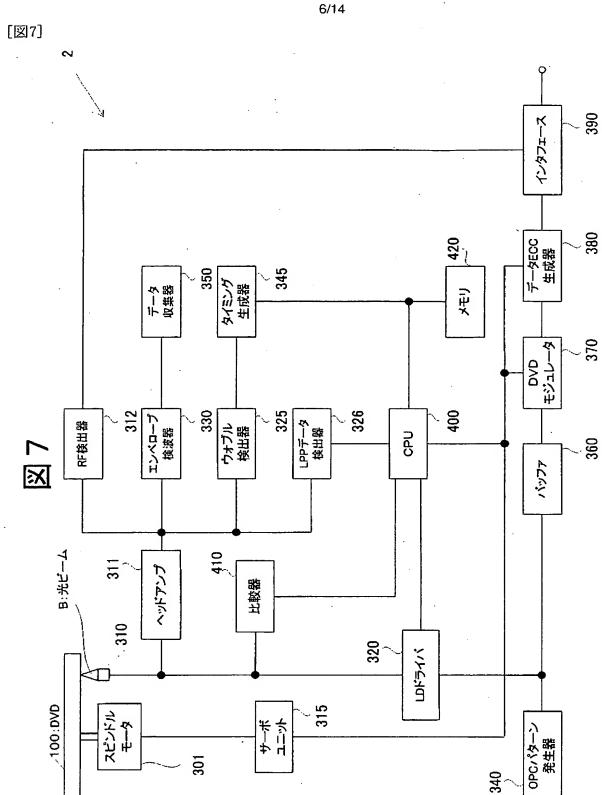


[図6]



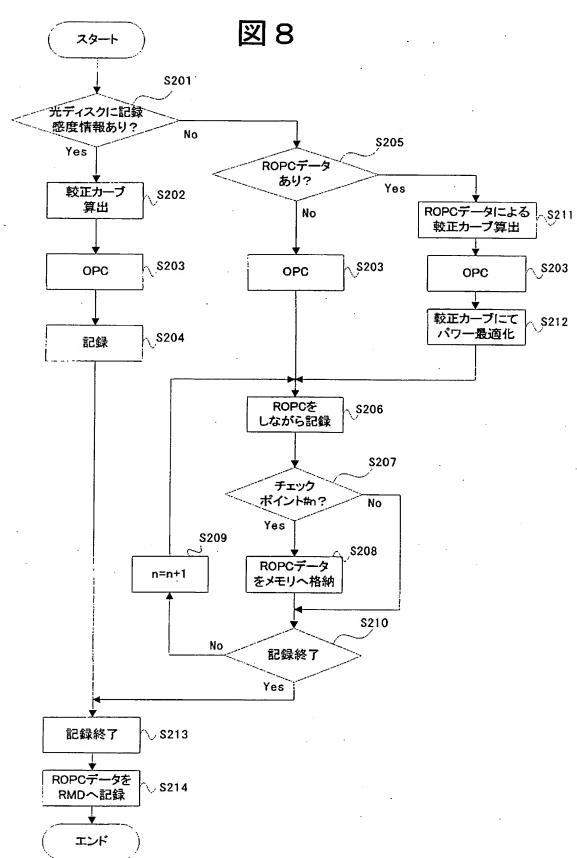




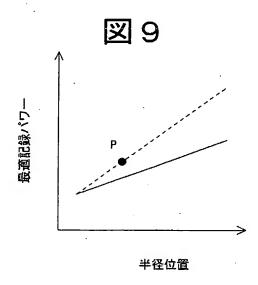


301

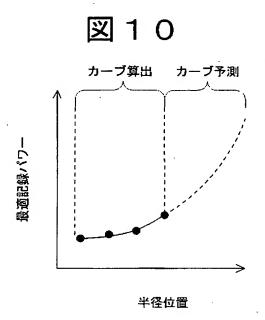




[図9]



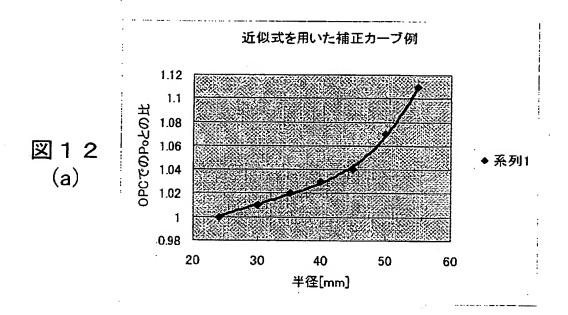
[図10]



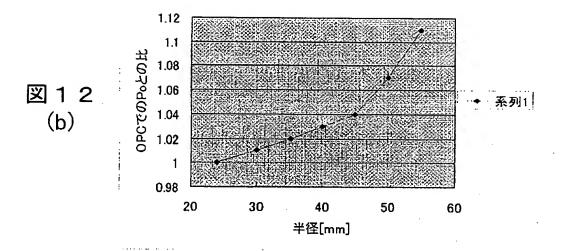
[図11]

図 1 1

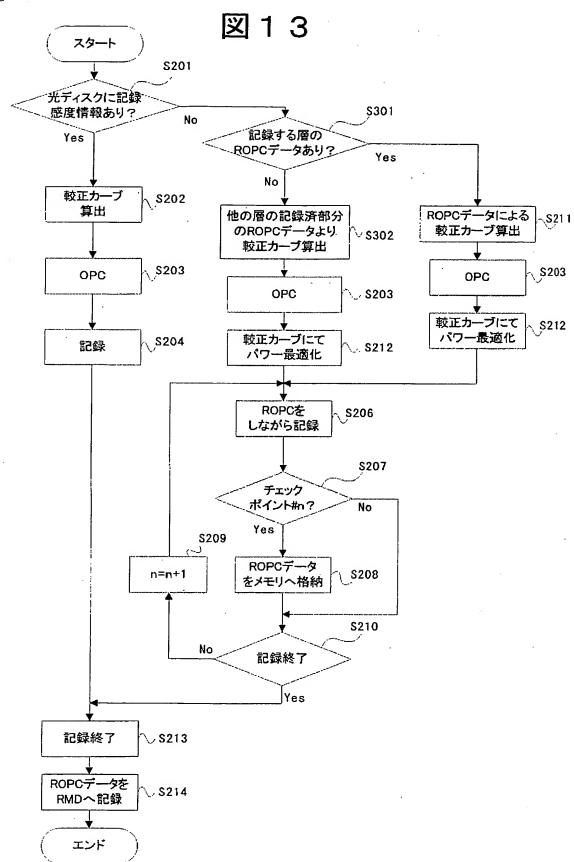
半径位置(mm)	記録パワーの比
24	1
30	1.01
35	1.02
40	1.03
45	1.04
50	1.07
55	1.11



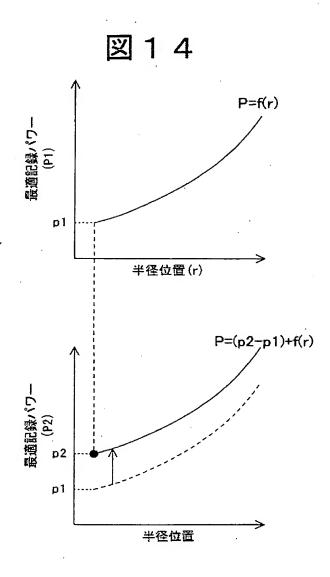
各ポイントを直線でつないだ補正カーブ例



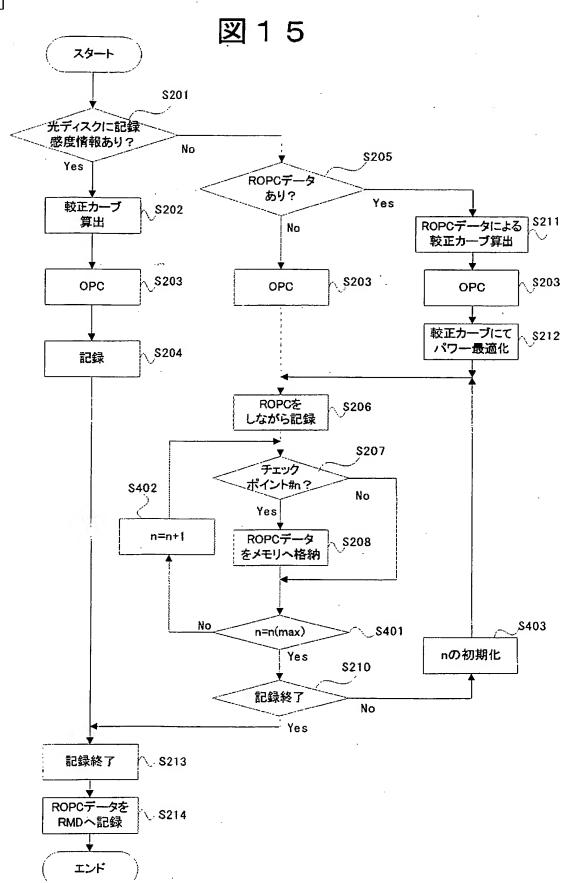
[図13]



[図14]



[図15]



[図16]

